						sity of Joi Engineer					
Department				Course Name			Course Number		er	Semester	
Mecha	inical Er	ngineering		Mechanics of	Mach	ines	0944331				
						atalog Desc					
	ation ar			ons, mobility and l chanisms. Inertia for							
					Inst	ructors					
Name				E-mail	Sec Office Hours			Lecture Time			
- juint					~~~						
Title			Г	Design of Machinery	lext	Books					
Author	(s)			Norton, R. L.							
-	Publisher, Year, Ed		McGraw Hill, Third Edition, (SI Units)								
	,	,			Refe	erences					
Books 1. Charles E. Wilson, J. Peter Sadler (1993) Kinematics and Dynamics of Machinery Edition. Harper Collins. 2. Waldron, Kinzel (2004) Kinematics, Dynamics, and Design of Machinery, second John Wiley& Sons						•					
Journals Mechanism and Machine Theory, www.elsevier.com/locate/mechmt											
Interne	t links			ac.in/courses/112104							
					Prere	quisites					
Prerequ	uisites by	y topic	Са	alculus, Vector Analys							
Prerequ	uisites by	y course	Dynamics 0904222								
Co-requ	uisites b	y course	-								
Prerequ	uisite for	•	М	lachine Design 2							
				Т	opics	Covered					
Week				Topics	-		Cha	pter in Tex	t	S	ections
1	Introd	uction Me	cha	-	appli	cations		ter 1		Sectio	
2	Introduction: Mechanisms and machines, Links, Joints, Degree of Freedom (Mobili				currons.	-	oter 2			.11, 2.13	
3-4				sition analysis: graphical and			-	oter 4		-4.12	.11, 2.15
3-4	analyt		051	ition analysis. graphi	analysis: graphical and			nel 4	4.0-	-4.12	
5-6			: gi	raphical and analytic	al.		Chap	oter 6	6.0-	-6.1,6.	3-6.7, 6.9
6-7	Accel	eration ana	lysi	is: graphical and ana	lytical		Chap	oter 7	7.0-	-7.1,7.	3,7.5-7.7
7-8	Static	& Dynami	c fo	orce analysis of mech	s.	Chapter 11 11.0-11		0-11.6	, 11.8		
9-10	Cams:	types of fo	ollowers and motion program				Chap	oter 8	8.0-	8.0-8.3, 8.6	
11-14		• •	parameters and different types of				Char	oter 9	9.0-	9.9.9	.11-9.12
	trains.	•	1	· ·	71-	0 -	r			- , -	

	Introc	duction to bala	ncing		Chapter 12 12.0-12.2									
		Map	ping of Cour	se Outcome	s to ABET	Student Outco	mes							
SOs				Cour	se Outcome	es								
1	 Ability to perform kinematic analysis of planar mechanisms and gear train including mobility, position, velocity, acceleration analysis, and force analysis. 													
2	2. Ability to perform dynamic analysis of planner mechanisms and perform static and dyna balancing.													
-	3. A	3. Ability to perform design of CAM-Follower systems and gear trains and planar mechanisms.												
	1			Evalu	ation									
Assess	sment T	ools	Expecte	Expected Due Date										
Projec	et							10 %						
1 st Mic	dterm]	Exam												
2 nd Mi	dterm	Exam												
Final I	Exam													
		Contr	ibution of Co	urse to Mee	t the Profe	ssional Compo	nents							
		ontributes to be nachine compo	onents.		-	tion and force a	nalysis and ba	asic design of						
				ionship to S	-	1								
	SOs 1		2	3	4	5	6	7						
Availa	bility	Х	Х											
		Relationsh	ip to Mechan	ical Engine	ering Prog	ram Objectives	(MEPOs)							
MEPO1 ME			MEPO2	ME	PO3	MEPO4	1	MEPO5						
			ABI	T Student (Outcomes ((SOs)								
						SOs) eering problems	by applying	principles of						
er	ngineeri	ng, science, an	formulate, and mathematics	nd solve com	plex engine									
er 2 A	ngineeri In abilit	ng, science, an y to apply eng	formulate, and mathematics ineering design	nd solve com	olutions that	eering problems	needs with co	nsideration of						
ег 2 А ри	ngineeri In abilit ublic he	ng, science, an y to apply eng alth, safety, an	formulate, and mathematics ineering design	nd solve com n to produce s rell as global,	oplex engine colutions that cultural, soc	t meet specified	needs with co	nsideration of						
2 A pu 3 A 4 J ju	ngineeri n abilit ublic he n abilit	ng, science, an y to apply eng alth, safety, an y to communic y to recognize ts, which must	formulate, and ad mathematics ineering design d welfare, as we ate effectively ethical and pro-	nd solve com n to produce s rell as global, with a range of fessional resp	olutions that cultural, soci of audiences	t meet specified	needs with con- l, and economic uations and m	nsideration of nic factors nake informed						
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